

EP 5 Core

Series/Type: B65855A

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EP 5

Core B65855A

- For small interface transformers and filter chokes
- Suitable for high precise feedthrough gapping
- Same footprint as EE 5
- A_I value increases about 40% against EE 5
- Winding area larger than EE 5
- Delivery mode: sets

Magnetic characteristics (per set)

 $\Sigma I/A = 3.149 \text{ mm}^{-1}$

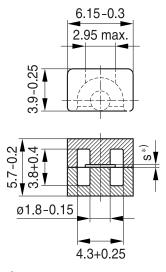
 $I_e = 9.73 \text{ mm}$

 $A_e = 3.09 \text{ mm}^2$

 $A_{min} = 2.30 \text{ mm}^2$

 $V_e = 30 \text{ mm}^3$

Approx. weight 0.5 g/set



*) gapped (one-sided)

FRM0363-C-E

Gapped (A_L values/air gaps examples)

Material	A _L value	μ_{e}	S	Ordering code
			approx.	
	nH		mm	
T38	16 ±3%	40	0.24	B65855A0016A038
	25 ±3%	63	0.15	B65855A0025A038
	40 ±5%	100	0.10	B65855A0040J038
	63 ±8%	158	0.06	B65855A0063D038

Ungapped

Material	A _L value nH	μ_{e}	Ordering code
N49	350 +30/–20%	880	B65855A0000R049
N92	350 +30/–20%	880	B65855A0000R092
N87	430 +30/–20%	1100	B65855A0000R087
N45	550 +30/–20%	1380	B65855A0000R045
T57	560 +30/–20%	1400	B65855A0000R057
T38	2000 +40/–30%	5000	B65855A0000Y038
T66	2200 +40/–30%	5500	B65855A0000Y066

Other A_L values/air gaps and materials available on request – see Processing remarks on page 3.



Cautions and warnings

Mechanical stress and mounting

Ferrite cores have to meet mechanical requirements during assembling and for a growing number of applications. Since ferrites are ceramic materials one has to be aware of the special behavior under mechanical load.

As valid for any ceramic material, ferrite cores are brittle and sensitive to any shock, fast temperature changing or tensile load. Especially high cooling rates under ultrasonic cleaning and high static or cyclic loads can cause cracks or failure of the ferrite cores.

For detailed information see data book, chapter "General - Definitions, 8.1".

Effects of core combination on A_I value

Stresses in the core affect not only the mechanical but also the magnetic properties. It is apparent that the initial permeability is dependent on the stress state of the core. The higher the stresses are in the core, the lower is the value for the initial permeability. Thus the embedding medium should have the greatest possible elasticity.

For detailed information see data book, chapter "General - Definitions, 8.1".

Heating up

Ferrites can run hot during operation at higher flux densities and higher frequencies.

NiZn-materials

The magnetic properties of NiZn-materials can change irreversible in high magnetic fields.

Ferrite Accessories

EPCOS ferrite accessories have been designed and evaluated only in combination with EPCOS ferrite cores. EPCOS explicitly points out that EPCOS ferrite accessories or EPCOS ferrite cores may not be compatible with those of other manufacturers. Any such combination requires prior testing by the customer and will be at the customer's own risk.

EPCOS assumes no warranty or reliability for the combination of EPCOS ferrite accessories with cores and other accessories from any other manufacturer.

Processing remarks

The start of the winding process should be soft. Else the flanges may be destroyed.

- Too strong winding forces may blast the flanges or squeeze the tube that the cores can not be mounted any more.
- Too long soldering time at high temperature (>300 °C) may effect coplanarity or pin arrangement.
- Not following the processing notes for soldering of the J-leg terminals may cause solderability problems at the transformer because of pollution with Sn oxyde of the tin bath or burned insulation of the wire. For detailed information see chapter "Processing notes", section 2.2.
- The dimensions of the hole arrangement have fixed values and should be understood as a recommendation for drilling the printed circuit board. For dimensioning the pins, the group of holes can only be seen under certain conditions, as they fit into the given hole arrangement. To avoid problems when mounting the transformer, the manufacturing tolerances for positioning the customers' drilling process must be considered by increasing the hole diameter.



Cautions and warnings

Display of ordering codes for EPCOS products

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Symbols and terms

Symbol	Meaning	Unit
A	Cross section of coil	mm ²
A_{e}	Effective magnetic cross section	mm ²
A_L	Inductance factor; A _L = L/N ²	nH
A_{L1}	Minimum inductance at defined high saturation ($\triangleq \mu_a$)	nH
A _{min}	Minimum core cross section	mm ²
A_N	Winding cross section	mm ²
A_R	Resistance factor; $A_R = R_{Cu}/N^2$	$\mu\Omega = 10^{-6} \Omega$
В	RMS value of magnetic flux density	Vs/m ² , mT
ΔB	Flux density deviation	Vs/m ² , mT
Ê	Peak value of magnetic flux density	Vs/m ² , mT
ΔÂ	Peak value of flux density deviation	Vs/m ² , mT
B_DC	DC magnetic flux density	Vs/m ² , mT
B_R	Remanent flux density	Vs/m ² , mT
B_S	Saturation magnetization	Vs/m ² , mT
C_0	Winding capacitance	F = As/V
CDF	Core distortion factor	mm ^{-4.5}
DF	Relative disaccommodation coefficient DF = d/μ_i	
d	Disaccommodation coefficient	
E_a	Activation energy	J
f	Frequency	s⁻¹, Hz
f _{cutoff}	Cut-off frequency	s−1, Hz
f_{max}	Upper frequency limit	s ^{−1} , Hz
f _{min}	Lower frequency limit	s−1, Hz
f _r	Resonance frequency	s ^{−1} , Hz
f_{Cu}	Copper filling factor	
g	Air gap	mm
Н	RMS value of magnetic field strength	A/m
Ĥ	Peak value of magnetic field strength	A/m
H_{DC}	DC field strength	A/m
H _c	Coercive field strength	A/m
h	Hysteresis coefficient of material	10 ⁻⁶ cm/A
h/μ_i^2	Relative hysteresis coefficient	10 ⁻⁶ cm/A
1	RMS value of current	Α
I_{DC}	Direct current	Α
Î	Peak value of current	Α
J	Polarization	Vs/m ²
k	Boltzmann constant	J/K
k_3	Third harmonic distortion	
k _{3c}	Circuit third harmonic distortion	
L	Inductance	H = Vs/A



Symbols and terms

Symbol	Meaning	Unit
Δ L/L	Relative inductance change	Н
L_0	Inductance of coil without core	Н
L _H	Main inductance	Н
L_p	Parallel inductance	Н
L _{rev}	Reversible inductance	Н
L _s	Series inductance	Н
l _e	Effective magnetic path length	mm
I _N	Average length of turn	mm
N	Number of turns	
P_{Cu}	Copper (winding) losses	W
P _{trans}	Transferrable power	W
P _V	Relative core losses	mW/g
PF	Performance factor	
Q	Quality factor (Q = $\omega L/R_s$ = 1/tan δ_l)	
R	Resistance	Ω
R_{Cu}	Copper (winding) resistance (f = 0)	Ω
R _h	Hysteresis loss resistance of a core	Ω
ΔR_h	R _h change	Ω
R _i	Internal resistance	Ω
R _p	Parallel loss resistance of a core	Ω
R_s	Series loss resistance of a core	Ω
R _{th}	Thermal resistance	K/W
R _V	Effective loss resistance of a core	Ω
S	Total air gap	mm
Т	Temperature	°C
ΔT	Temperature difference	K
T_{C}	Curie temperature	°C
t	Time	s
t_v	Pulse duty factor	
tan δ	Loss factor	
tan δ_l	Loss factor of coil	
tan δ_r	(Residual) loss factor at H $ ightarrow$ 0	
tan $\delta_{\rm e}$	Relative loss factor	
tan δ_h	Hysteresis loss factor	
tan δ/μ _i	Relative loss factor of material at H \rightarrow 0	
U	RMS value of voltage	V
Û	Peak value of voltage	V
V _e	Effective magnetic volume	mm ³
Z	Complex impedance	Ω
Z _n	Normalized impedance $ Z _n = Z /N^2 \times \varepsilon (I_e/A_e)$	Ω/mm



Symbols and terms

Symbol	Meaning	Unit
α	Temperature coefficient (TK)	
α_{F}	Relative temperature coefficient of material	1/K
α_{e}	Temperature coefficient of effective permeability	1/K
ϵ_{r}	Relative permittivity	
Φ	Magnetic flux	Vs
η	Efficiency of a transformer	
η _B	Hysteresis material constant	mT-1
η _i	Hysteresis core constant	
$\lambda_{\sf s}$	Magnetostriction at saturation magnetization	
ı	Relative complex permeability	
ι_0	Magnetic field constant	Vs/Am
la	Relative amplitude permeability	
^l app	Relative apparent permeability	
le	Relative effective permeability	
ιį	Relative initial permeability	
ι _p '	Relative real (inductive) component of $\overline{\mu}$ (for parallel components)	
ι _p "	Relative imaginary (loss) component of $\overline{\mu}$ (for parallel components)	
ι_{r}	Relative permeability	
ι_{rev}	Relative reversible permeability	
ι _s '	Relative real (inductive) component of $\overline{\mu}$ (for series components)	
ι _s "	Relative imaginary (loss) component of $\overline{\mu}$ (for series components)	
ι_{tot}	Relative total permeability	
	derived from the static magnetization curve	
)	Resistivity	Ω m $^{-1}$
ΣΙ/A	Magnetic form factor	mm ⁻¹
^r Cu	DC time constant $\tau_{Cu} = L/R_{Cu} = A_L/A_R$	s
ω	Angular frequency; ω = 2 Π f	s ⁻¹

All dimensions are given in mm.





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- 2. We also point out that in individual cases, a malfunction of electronic components or failure before the end of their usual service life cannot be completely ruled out in the current state of the art, even if they are operated as specified. In customer applications requiring a very high level of operational safety and especially in customer applications in which the malfunction or failure of an electronic component could endanger human life or health (e.g. in accident prevention or life-saving systems), it must therefore be ensured by means of suitable design of the customer application or other action taken by the customer (e.g. installation of protective circuitry or redundancy) that no injury or damage is sustained by third parties in the event of malfunction or failure of an electronic component.
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